



# Collaborative Wire Harness Design in PLM Environment

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- Mechatronics overview
- Wire Harness Design Challenges
- Collaborative Framework
- Use cases

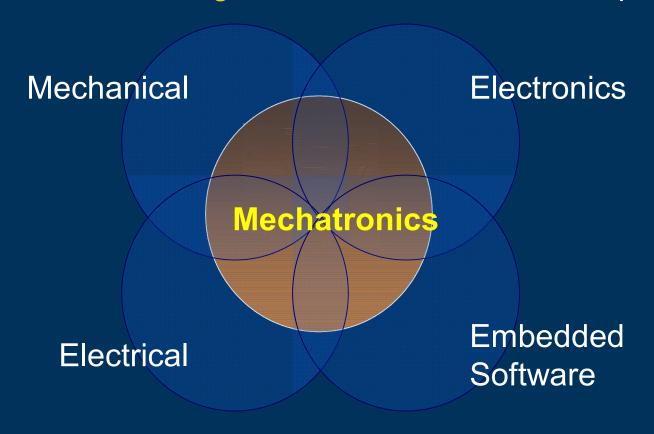




### **Mechatronics Definition**



▶ A mechatronics system is the synergistic integration of mechanical, electrical, electronics and embedded software technologies into electro-mechanical products.





#### Some Facts...



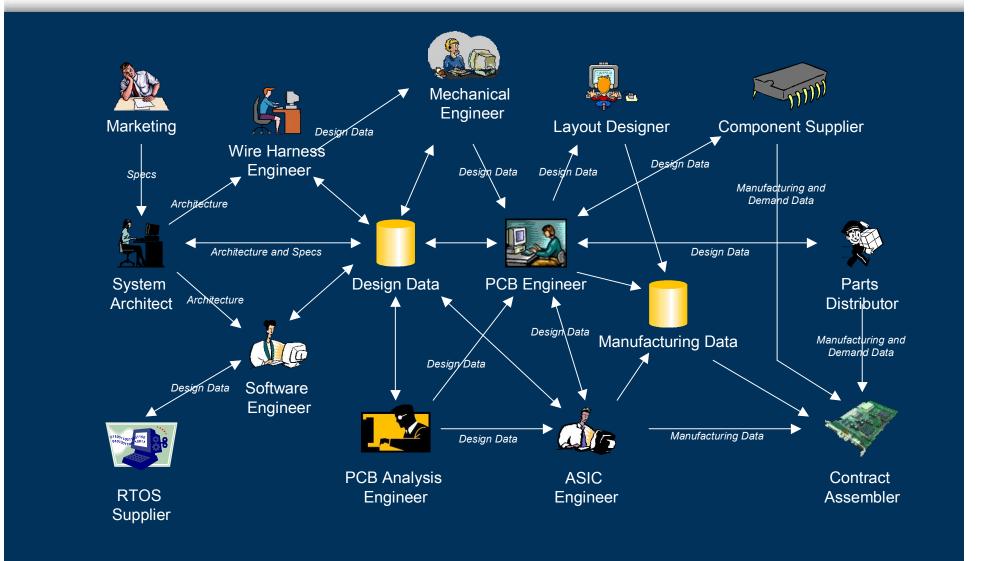
- Rapidly Increasing Functionality
  - Increased package and PCB density
  - ▶ 80-90% of new functions are electronics based¹
  - Rapidly changing technology
  - Increased on-board diagnostics
  - Software-based functionality
- Growing Networks
  - Hundreds of kilometers of wires in an aircraft
  - ► Complex interconnections
- Tighter Physical Constraints
  - Smaller enclosures
  - Increased number of components
  - ► Electromagnetic interference
  - Non-planar, flexible circuitry





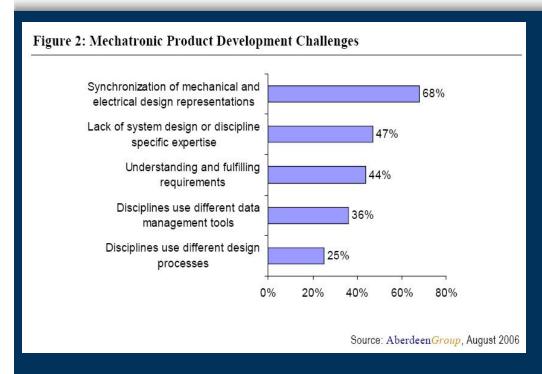
## **Mechatronics Design Environment**











- ► Synchronization of mechanical and electrical design representations
- ► Lack of system design
- ► Understanding and fullfilling requirements
- ► Disciplines use different data management
- ► Disciplines use different design processes
- ► Lack of or no smooth flow of data across all phases





**Significant Value** 







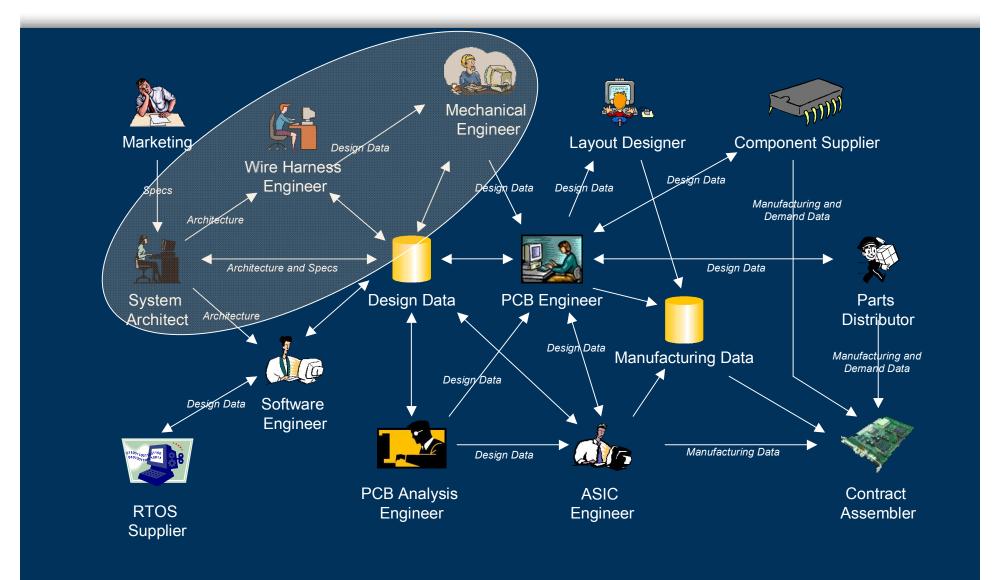
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## Wire Harness design focus...







# Challenges associated with Wire Harness Design Process...



- Developers designed and located each sub-assembly in the system with little consideration of the physical and electrical constraints of cabling
- Determine precise routing and length of cable through trial and error
- Synchronization of mechanical and electrical design data
- Lack of Interoperability between tools
- Disciplines use different data management
- ► Disciplines use different design processes
- Lack of or no smooth flow of data across all phases
- Lack of Change control
- ► Lack of support for Option and Variant management of Max complexity wire harness



## **Evolution of Wire Harness Design**



Some of the challenges are addressed by integrating ECAD system with Mechanical 3-D modeling system

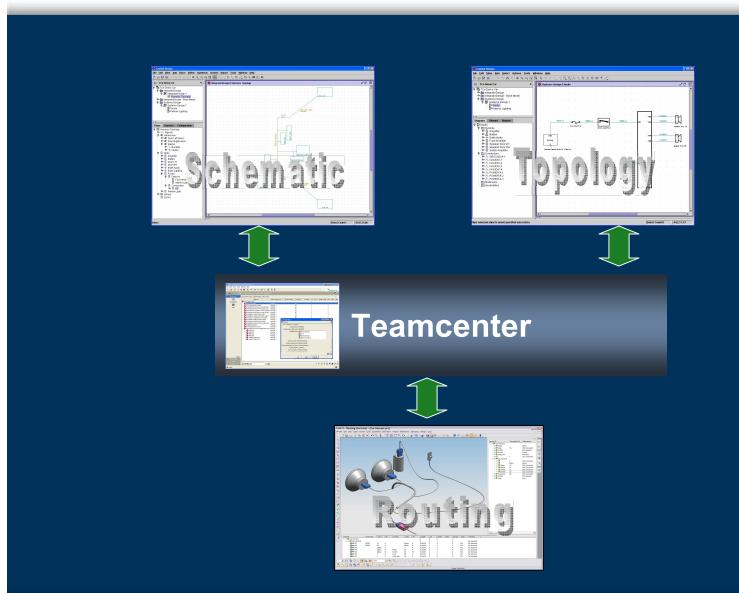


- Precise Routing
- Exact length of Cable & Bundle data
- Interference checks
- Design Rule Validation
- Lack of integrated workflow resulting
  - Duplication of design data
  - Modification of data is error prone and time consuming.
- Lack of change control
- Point to point integration between multiple design tools



## Vision of Harness Design







### **Teamcenter PLM**



#### **▶** Core Capabilities

- **▶** Security
- **▶ Change Management**
- **▶** Configuration Management
- **▶** Data Distribution
- **►**Workflow
- **▶** Collaboration

#### ▶ Wire Harness Design

- ►AP212/KBL data model
- **▶PLM XML** support
- ▶ITK, AIWS API support
- ▶Integration framework





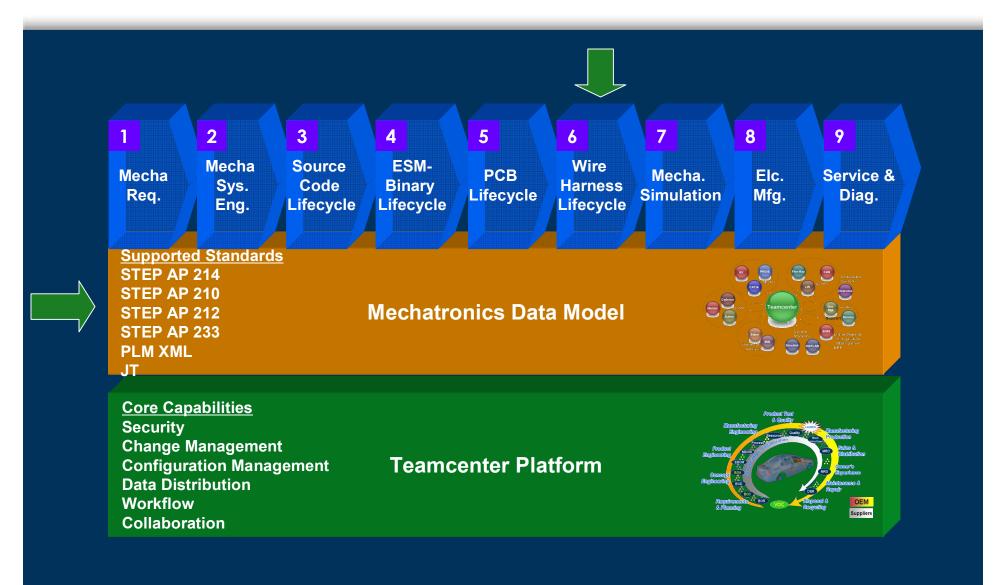
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## **UGS Mechatronics Framework**





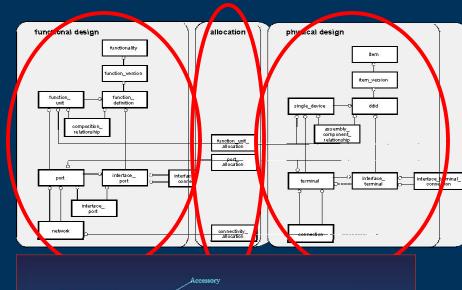


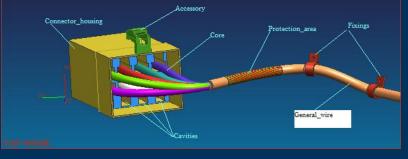
### **Wire Harness Data Model**

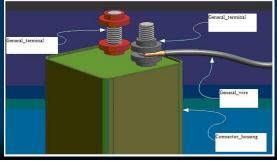


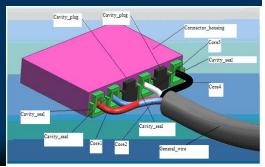
- ► Data model based on Industry standard STEP model AP212
- Provide objects to support entire design process –
  - ► Functions, Connections, Signals, Ports, Routing, Topology etc for Logical Design
  - ▶ Items, Devices for Physical Design
- Allocations to associate components across different phases of development

► Optionally, support KBL specific data elements - general\_wire, general\_terminal, cavity\_plug, cavity\_seal



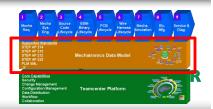




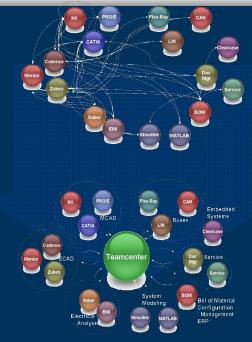




# Wire Harness Data Model contd...



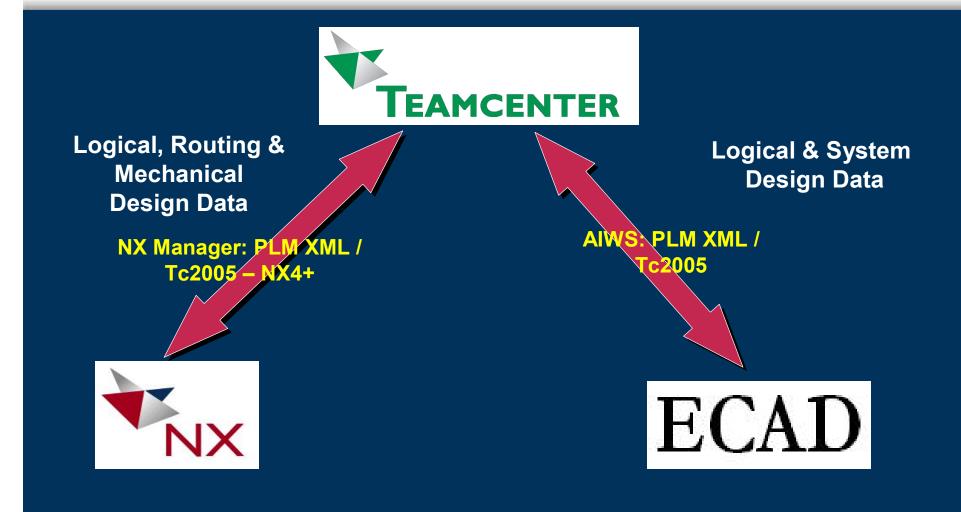
► Goal is to integrate the design environment so data can be shared seamlessly between different application environments





## **Integration Architecture**



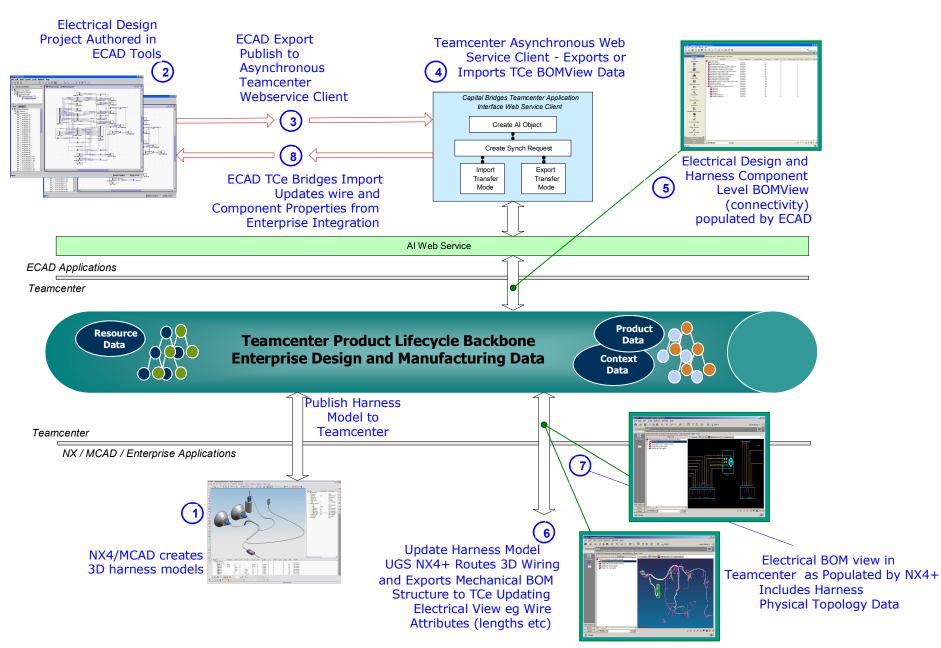






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**Use Case – Wiring Design and Release** 





- Better Integration between 2-D schematic and 3-D Mechanical systems
- Integration provides the ability to design in context
- Unique master data in Teamcenter shared across all stages of design
- Ability to manage workflow and change control





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